Atop Technologies, Inc.

SDK Porting Guide

User Manual

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We have checked the contents of this manual for agreement with the hardware and the software described. Since deviations cannot be precluded entirely, we cannot guarantee full agreement. However, the data in this manual is reviewed regularly and any necessary corrections will be included in subsequent editions.

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1 Preface

1.1 *Purpose of the Manual*

This manual supports the user with effective steps for SDK porting. As such, it contains some advanced network management knowledge, instructions, examples, guidelines and general theories designed to help users manage this device and its corresponding software. A background in general theory is necessary when reading it. Please refer to the Glossary for technical terms and abbreviations (if any).

1.2 *Who Should Use This User Manual*

This manual is to be used by qualified network personnel or support technicians who are familiar with embedded Linux or C-programming skill. It might be useful for system programmers or network planners as well. This manual also provides helpful and handy information for first time users. For any related problems, please contact your local distributor. If they are unable to assist you, please redirect your inquiries to www.atop.com.tw or www.atoponline.com.

2 Introduction

ATOP SDK (software development kit) is a software package which helps you to easily implement applications on ATOP platforms. This document provides you with a quick and easy guide to help you implement functions with ATOP SDK.

3 Software Block Diagram

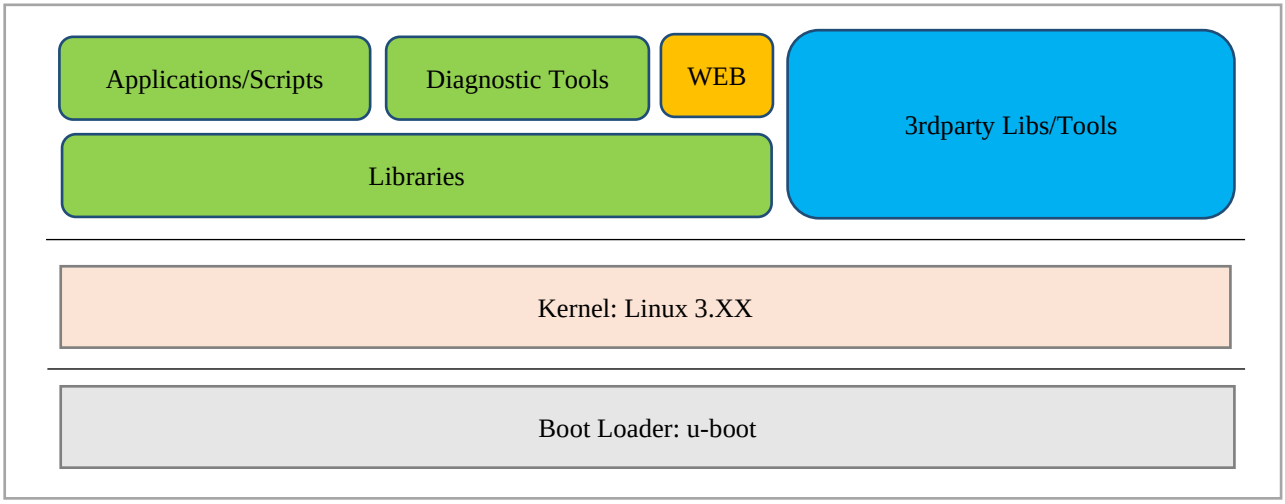


Figure 1: Software block diagram

Folder	Description
Bootloader	ATOP SDK support u-boot as the bootloader
Kernel	The OS used by ATOP SDK is the Linux
Libraries	The libraries provide some ATOP proprietary APIs for users to easy access system or peripheral components.
Applications/Scripts	SDK provides some basic applications and scripts to bring up network and some basic services.
Diagnostic tools	The “Diagnostic tools” are available for users to test and verify peripheral components.
WEB	SDK package uses the lighttpd as the WEB server. The simple WEB server helps users to manage system settings.
3rd Party Tools/Library	3rd party tools and libraries used in SDK

Table 1: SDK folders and description

4 Source Architecture

Below figure illustrates the source architecture of SDK:

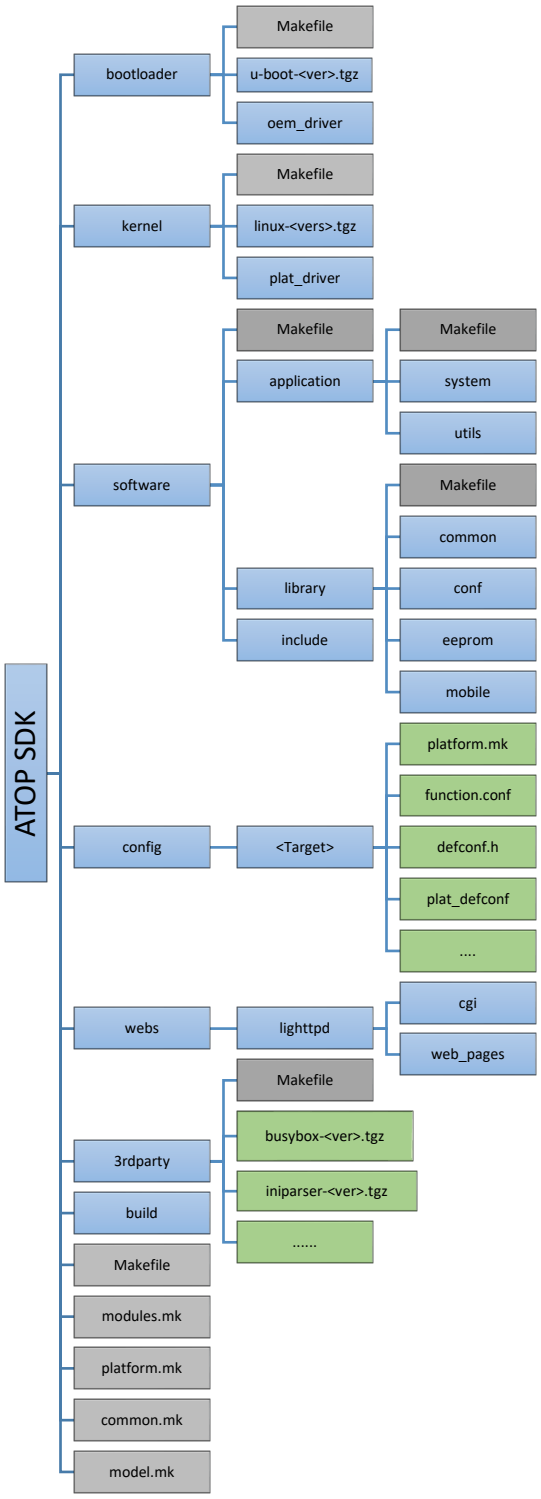


Figure 2: Source architecture of SDK

Folders	Descriptions
3rd Party	All 3rdparty tools and libraries are put under this folder.
Bootloader	This folder collects the boot source and related object codes.
Build	After source code is compiled successfully, generated images are put in this folder.
Config	This folder collects the platform/target configurations.
File System	This folder collects default scripts files and contents of image file system.
Kernel	This folder collects the kernel source and related object codes.
Software	This folder collects ATOP proprietary applications, libraries, and diagnostic tools.
Webs	This folder collects the WEB CGI files, pages and java scripts files.

Table 2: Source architecture's folders and description

5 Build Enviornment Setup

Supported operating system:

1. Ubuntu-16.04 (i386)
2. Ubuntu-18.04 (x64)

- For TI platform, install the toolchain to “/opt/ti-am335x-linux-devkit-08.00.00.00”
- For Nuvoton platform, install the toolchain to “/usr/local/arm_linux_4.8”
- Following below steps to setup build environment

5.1 *Ubuntu 16.04 (i386)*

These are the following steps you need to undertake to setup the build environment in Ububtu 16.04 (i386):

1. Copy and decompress the tool chain to build host
   (ti-am335x-linux-devkit-08.00.00.00.tar.bz2)

   TI Platform
   # sudo cp ti-am335x-linux-devkit-08.00.00.00.tar.bz2 /opt/
   # cd /opt/; sudo tar jxf ti-am335x-linux-devkit-08.00.00.00.tar.bz2

   Nuvoton sPlatform
   # sudo cp arm_linux_4.8_nuvoton.tgz /usr/local/
   # cd /usr/local/; sudo tar zxf arm_linux_4.8_nuvoton.tgz

2. Edit the bashrc file
   # vi ~/.bashrc

   Add the line mentioned below at the end of the file to set environment while system start-up

   TI Platform
   export PATH=/opt/ti-am335x-linux-devkit-08.00.00.00/bin:$PATH

   Nuvoton Platform
   export PATH=/usr/local/arm_linux_4.8:$PATH

3. Install essential components

   $ sudo apt-get install git fakeroot build-essential ncurses-dev xz-utils kernel-package openssl libssl-dev autotools-dev autoconf libtool

4. Install image generating tools

   sudo apt-get install genext2fs u-boot-tools

5. Build libraries for ip tables (required only in case of ip table full support)

   $ sudo apt-get install flex bison libnfnetlink-dev libnetfilter-conntrack-dev libnetfilter-log-dev

6. Build libraries for glib (Required only in case of glib support)

   $ sudo apt-get install pkg-config libmount-dev libpcre3-dev

5.2 *Ubuntu 18.04 (x64)*

These are the following steps you need to undertake to setup the build environment in Ububtu 18.04 (x64):

1. Copy and decompress the tool chain to build host (ti-am335x-linux-devkit-08.00.00.00.tar.bz2)

   #TI:

   $sudo cp ti-am335x-linux-devkit-08.00.00.00.tar.bz2 /opt
   $sudo tar jxf ti-am335x-linux-devkit-08.00.00.00.tar.bz2 /opt

   # Nuvoton:

   $sudo cp arm_linux_4.8_nuvoton /usr/local
   $ cd /usr/local/; sudo tar zxfarm_linux_4.8_nuvoton.tgz

2. Edit the file of ".bashrc"

   $ vi ~/.bashrc
   # Add below line

   ...

   export PATH=/opt/ti-am335x-linux-devkit-08.00.00.00/bin:$PATH

   #or

   #export PATH=/usr/local/arm_linux_4.8/bin:$PATH

3. Install essential components

   $ sudo apt-get install git fakeroot build-essential ncurses-dev xz-utils kernel-package openssl libssl-dev autotools-dev autoconf libtool

4. Instal image generating tools

   $ sudo apt-get install genext2fs u-boot-tools

5. For Linux 18.04, enable i386 architecture first

   $ sudo dpkg --add-architecture i386
   $ sudo apt-get update

6. Install 32-bit libraries

   $ sudo apt-get install lib32ncurses5 lib32z1

$ sudo apt-get install libstdc++6:i386 libncurses5:i386 libz1:i386 libc6:i386 libc6-dev-i386 g++-multilib

7. Switch shell from dash to bash

   $ sudo dpkg-reconfigure dash
   *#Select **no** when prompted*

8. Build libraries for glib (Required only when glib support)

   $ sudo apt-get install pkg-config libmount-dev libpcre3-dev

6 Source Code Compilation

Most of the compiling methods are supported in *<sdk>/modules.mk*. Here are the basic commands used to compile the sources and generate the image files:

1. Build the whole system image (filesystem and image) - *$ make release_all*
2. Build the bootloader image (boot) only - *$ make uboot*
3. Build the system image (build with kernel without bootloader) - *$ make release_img*
4. You may also try to use this command to generate the system image without building the kernel source (Make sure kernel built successfully at first time) - *$ make image*
5. Compile the folders of software and webs, then generate the image - *$ make fwimg*
6. Compile the software folder - *$ make swbuild*
7. Compile the web folder - *$ make websvr*
8. Compile the 3rd party folder - *$ make opensrc*

Here is an example how to generate the bootloader and system images:

1. Switch to SDK repository - $ *cd <your working spaces>*
2. Type this command to compile sources, and generate the bootloader and firmware image – *$ make release_all*
3. For compiling the sources for the first time, system may ask for the "Select Build Target" and "Gen default target". (If not, you can ignode this step)
    - Select Build Target: <Your target platform to compile> (Ex: ATSDKC_A2201 is SDK for SE5901b platform)
    - Gen default target: y (Please type "y", thus there is no need to specify build target in next build)

Figure 3: Selecting build target

4. After build is successful, the boot and system images would be generated in the folder - "<SDK>/build"

   $ <TARGET>.dld // for system
   $ uboot.dld // for bootloader

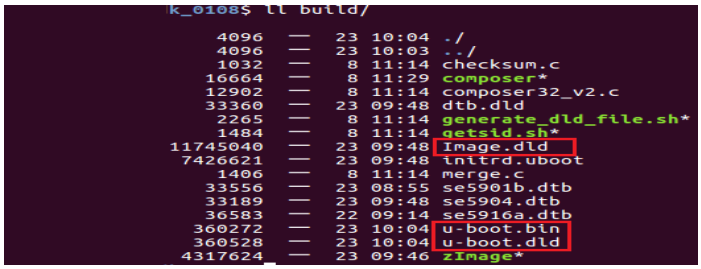


Figure 4: Generating boot and system images

7 Upgrade system/firmware image to hardware platform

In total there are three ways to upgrade the system/firmware images to hardware platforms:

7.1 *Upgrade system image or bootloader from bootloader (with TFTP protocol)*

Here are the following steps:

1. Copy generated firmware of “Image.dld” (or <Target>.dld or ***u-boot.dld***) to tftp server folder (tftpd32/64)

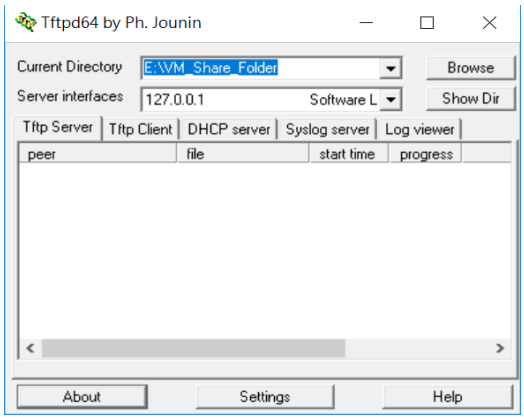


Figure 5: Copying generated firmware to tftp server folder

2. Reset the target device and press the “ESC” button to enter boot shell command menu

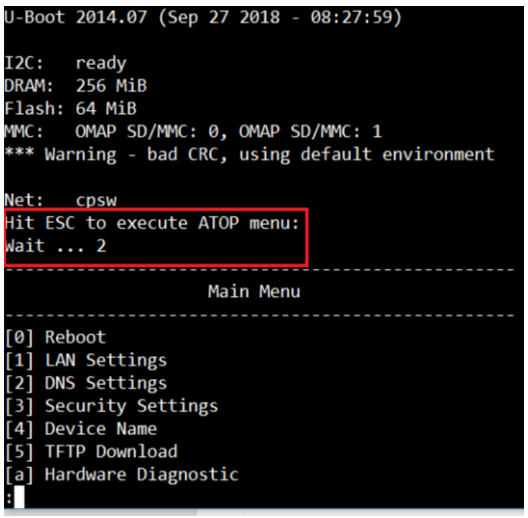


Figure 6: Reseting target device

3. Type “5” to enter “TFTP Download” mode

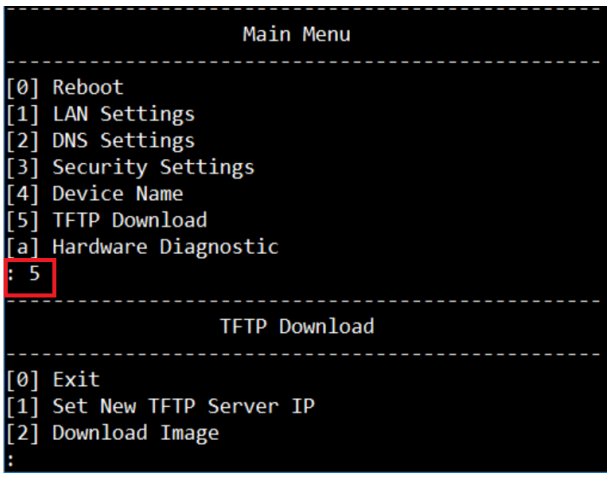


Figure 7: Entering TFPT Download mode

4. Type “1” to input correct TFTP server address

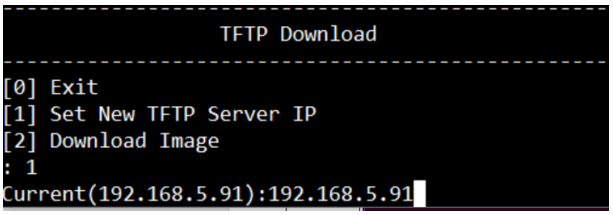


Figure 8: Input TFPT server address

5. Type “2” and input the file name of “Image.dld” (or <Target>.dld). Then type “Enter” to activate the firmware upgrade progress

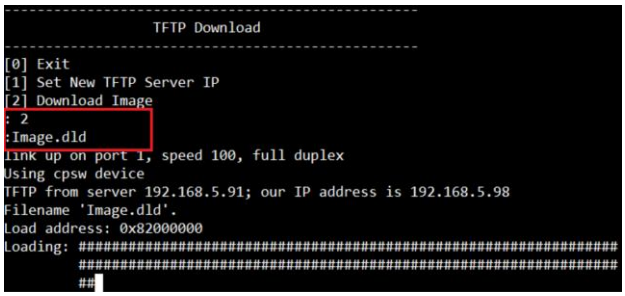


Figure 9: Input file name of “Image.dld”

6. After firmware is upgraded successfully, reset the target device and make sure it can start-up properly. (Manual press “0”-> “0” to reset device)

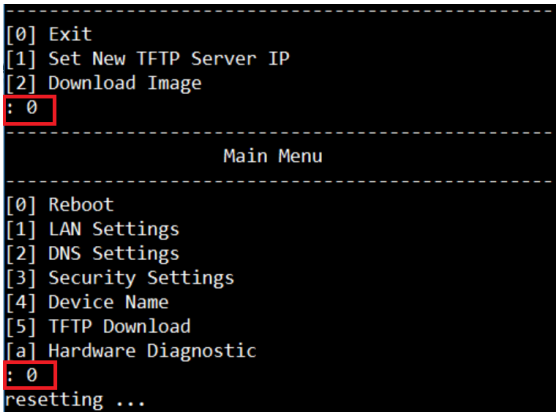


Figure 10: Resetting target device

7.2 *Upgrade system image or bootloader through WEB page*

Here are the steps you need to follow:

1. Login to WEB page (default account/password: admin/default)
2. Switch to Firmware Upgrade

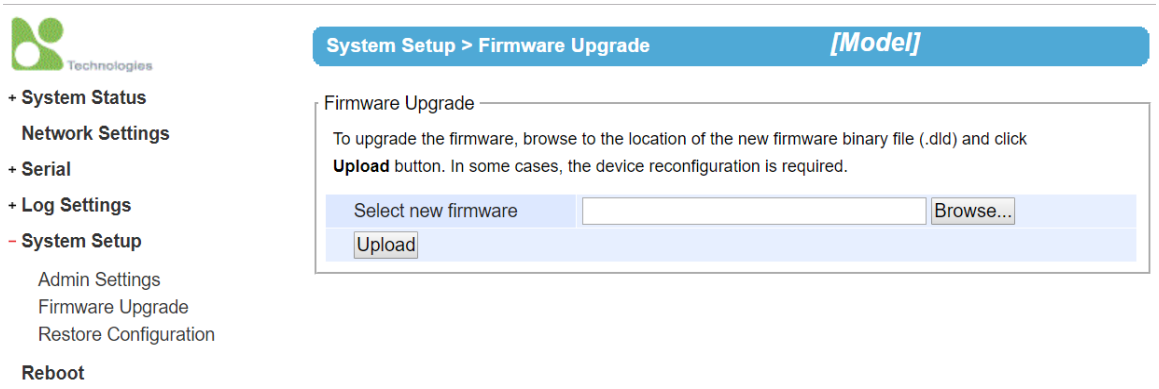


Figure 11: Login to ATOP SDK webpage

3. Click “Browser...” button to select firmware (Image.dld) from local host

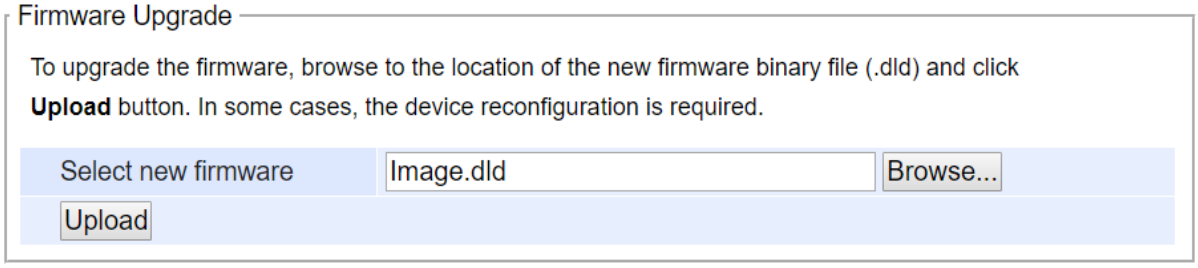


Figure 12: Select firmware from local host

4. Click “Upload” button to upload image to device

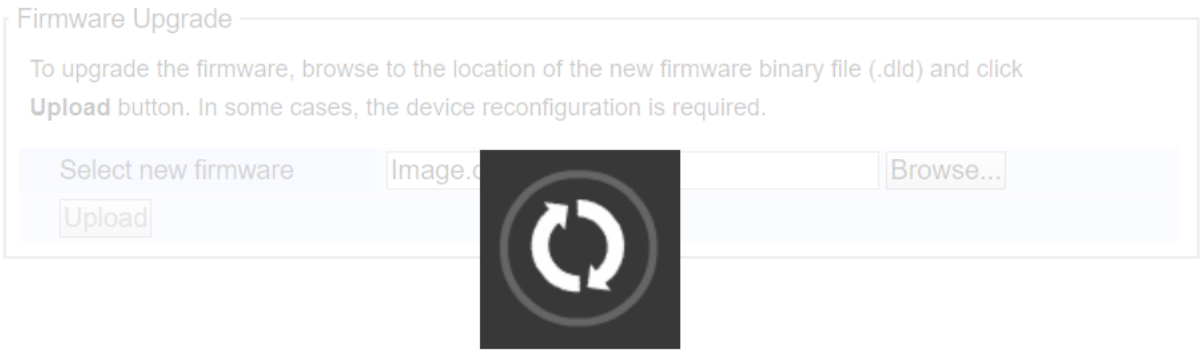


Figure 13: Upload image to device

5. Click “Ok” to start the firmware upgrade process

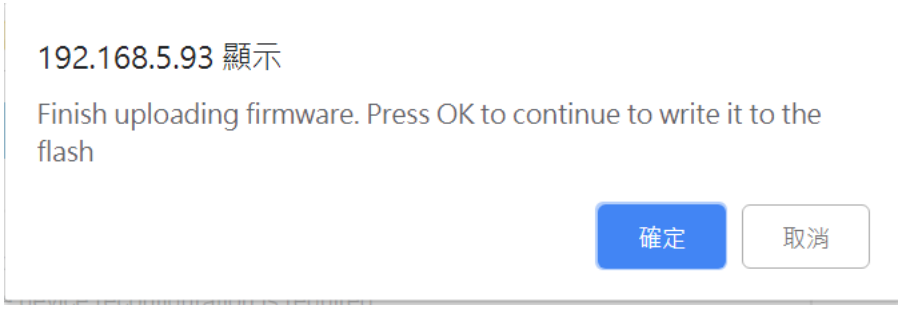


Figure 14: Starting firmware process

6. Click “Ok” to finish the firmware upgrade process and reset device

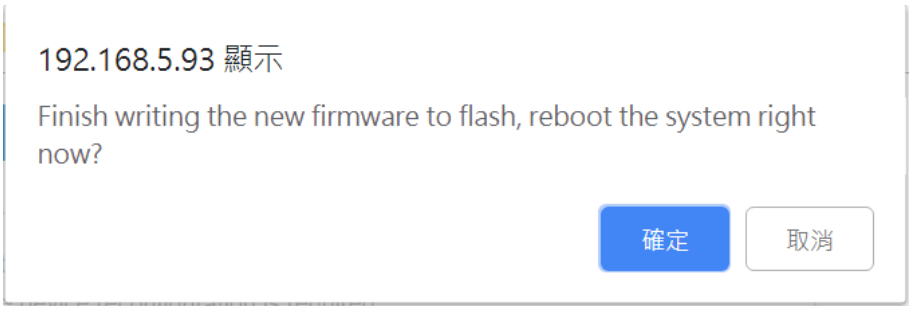


Figure 15: Finishing firmware process

7. Check if firmware has upgraded successfully after the device is rebooted

7.3 *Manually upgrade system image or bootloader from debug console*

Here are the steps to manually upgrade system image or bootloader from debug console:

1. Start the TFTP server and copy generated firmware to tftp server folder (tftpd32/64)

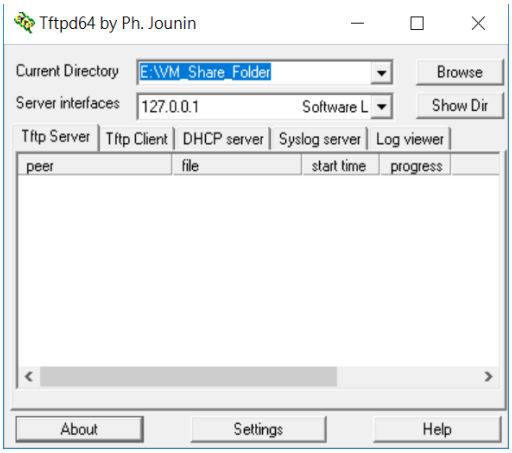


Figure 16: Copying generated firmware to tftp server folder

2. Login to debug console window (default account/password: root/none; baudrate: 115200)

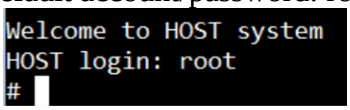


Figure 17: Login to debug console window

3. Execute below command to activate the FW upgrade progress
   # frmwr-upgrd tftp <ftp svr. Addr> <fw image>

   Note: fw image can be system image (xxx.dld), boot image (u-boot.dld), or device Tree (dtb.dld)

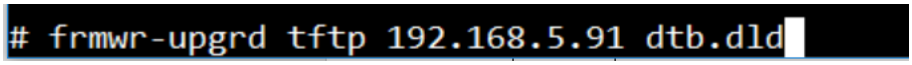


Figure 18: Activating FW upgrade process

4. Check if system resets automatically after FW upgrade

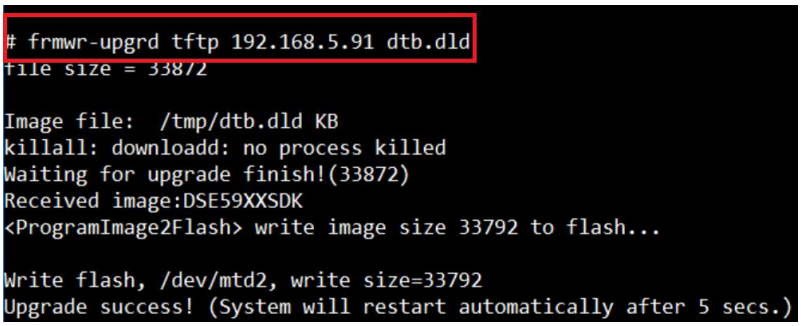


Figure 19: Checking auto-system reset

5. Check if system starts-up properly

8 Platform APIs

This section introduces APIs that are available in the SDK package. With these APIs, users can easily access/control peripheral components.

Note: API support varies on different platforms

8.1 *Buzzer*

API Name	void BuzzerOnOff(int onoff)
Descriptions	Turn on/off the platform's buzzer
Input	onoff: - 1: buzzer on - 0: buzzer off
Output	NA
Return	NA
Example	#include "buzzer.h" … // Buzzer on BuzzerOnOff(1); …

Table 3: API for buzzer

8.2 *Run Led*

API Name	void setRunLed(RUNLED_HANDLER *pHandler)
Descriptions	Handle the behaviors of "Run LED"
Input	pHandler: the pointer of RUNLED_HANDLER `typedef struct __runled_handler__ {` `  unsigned char  type;` `  unsigned char  action;` `  unsigned int  delay_on;` `  unsigned int  delay_off;` `} RUNLED_HANDLER;` - type: 0: none 1: solid on/off 2: blink 3: blink as heart beat - action: 0: LED off 1: LED on - delay_on: interval of LED on - delay_off: interval of LED off
Output	NA
Return	NA
Example	#include "runled.h" ... RUNLED_HANDLER handler; handler.type= 2; // blink handler.action= 1; // on handler.delay_on= 1000; // on interval, 1000 ms handler.delay_on= 500; // off interval; 50ms SetRunLed(&handler); ...

Table 4: API for Run LED

8.3 *Alarm Led*

API Name	void setAlarmLed(unsigned int onoff)
Descriptions	Turn of/off the alarm led
Input	onoff: 0: off 1: on
Output	NA
Return	NA
Example	#include “alarmled.h” … // Turn on alarm LED SetAlarmLed(1); …

Table 5: API for Alarm LED

8.4 *DI, DO*

API Name	void sysGetDI(in index)
Descriptions	Get DI pin status
Input	index: Index of pin
Output	NA
Return	NA
Example	#include “di.h” … //Get DI0 pin status SysGetDI(0); …

Table 6: API for DI

API Name	void sysSetDO(int index, in value)
Descriptions	Set DO state
Input	index: Index of pin value: 0: off 1: on
Output	NA
Return	NA
Example	#include “alarmled.h” … // Set DO0 on SysSetDO(0, 1); // Set DO1 off SysSetDO(1, 0); …

Table 7: API for DO

8.5 *HW watchdog (TI plarform only)*

API Name	void hwd_enable(void)
Descriptions	Enable HW watchdog
Input	NA
Output	NA
Return	NA
Example	#include “sys_hwd.h” … // enable HW watchdog hwd_enable(); …

Table 8: API for HW watchdog

API Name	void hwd_disable(void)
Descriptions	Disable HW watchdog

Input	NA
Output	NA
Return	NA
Example	#include “sys_hwd.h” … // enable HW watchdog hwd_disable(); …

Table 9: API for HW watchdog

API Name	void hwd_clear(void)
Descriptions	Clear HW watchdog timer count
Input	NA
Output	NA
Return	NA
Example	#include “sys_hwd.h” … // clear HW watchdog hwd_clear(); …

Table 10: API for HW watchdog

API Name	void hwd_time(int interval)
Descriptions	Set HW watchdog timer interval
Input	Interval: interval of timeout (sec)
Output	NA
Return	NA
Example	#include “sys_hwd.h” … // Set HW watchdog timer interval to 10 secs hwd_timeout(10); …

Table 11: API for HW watchdog

8.6 *COM Management*

API Name	Int SysUARTNumber(void)

Descriptions	Query supported number of COM ports
Input	NA
Output	NA
Return	Number of supported COM ports
Example	#include “sys_uart.h” … // Get COM port number Int num = SysUARTNumber(); …

Table 12: API for COM Management

API Name	void comport_init()
Descriptions	Initialize COM ports depending on COM configurations
Input	NA
Output	NA
Return	NA
Example	#include “comport.h” … // Depending on COM settings to Initialize physical port settings comport_init(); …

Table 13: API for COM Management

API Name	int comport_set(unsigned char index, void *pConf)
Descriptions	Set COM port configurations
Input	Index: Index of physical COM port

	pConf: pointer of COM port handler (COM_CONFIG) `/* COM_CONFIG:` ` * Description:` ` *  Structure for COM settings` ` *` ` *` ` */` `typedef struct __com_config__ {` `  /* Basic COM port settings */` `  unsigned char  u8Mode;  /*<-- COM port mode; 0:RS232, 1:RS422, 2:RS485, 3:RD485-4wire */` `  unsigned char  u8Parity;  /*<-- Parity check; 0:None, 1:Odd, 2:Even, 3:Mark, 4:Space */` `  unsigned char  u8Databit;  /*<-- Data bit code; 0:7 bit, 1:8 bit */` `  unsigned char  u8Stopbit;  /*<-- Stop bit code; 0:1 bit, 1:2 bit, */` `  unsigned char  u8Flowctl;  /*<-- Flow control; 0:none, 1:Xon/Xoff, 2:Hardware */` `  unsigned char  u8Xon;  /*<-- XON */` `  unsigned char  u8Xoff;  /*<-- XOFF */` `  unsigned char  u8Passthru;  /*<-- XON, XOFF Passthrough */` `  unsigned int  u32Baudrate;  /*<-- Baudrate */` `} COM_CONFIG;`
Output	NA
Return	NA
Example	`#include “com_conf.h”` `#include “comport.h”` … `  COM_CONF conf;` `  memset(&conf, 0, sizeof(COM_CONF));` `  conf.u8Mode = 0;  // RS-232` `  conf.u8Parity = 0;  // none` `  conf.u8Databit = 1;  // 8 bit` `  conf.u8Stopbit = 0;  // 1 bit` `  conf.u8Xon = 0xff;  // 0xff` `  conf.u8Xoff = 0xff;  // 0xff` `  conf.u8Mode = 0;  // RS-232` `  conf.u8Passthru = 0;  // none` `  conf.u32Baudrate = 115200;  // 115200` `  // Set COM0 settings` `  comport_set(0, &conf);` …

Table 14: API for COM Management

8.7 *Relay*

API Name	void SetRelayOnOff (unsigned int onoff)
Descriptions	Switch relay state: on or off
Input	onoff: 0: off 1: on

Output	NA
Return	NA
Example	#include “relay.h” … // Set Relay state to on SetRelayOnOff(1); …

Table 15: API for Relay

8.8 *Log*

API Name	void SendSysLog (severity_e serv, char *prefix, char *msg)
Descriptions	Send messages to Log file
Input	serv: EVT_INFO EVT_WARN EVT_ERR prefix: Prefix information LOG_SYS: “Sys” LOG_NET: “Net” msg: Message contents
Output	NA
Return	NA
Example	#include “loginfo.h” … // Set Relay state to on SendSysLog(EVT_INFO, LOG_SYS, “This is a test!”); …

Table 16: API for Log

API Name	void SendSysLog (severity_e serv, char *prefix, char *msg)
Descriptions	Send messages to Log file
Input	serv: EVT_INFO EVT_WARN EVT_ERR prefix: Prefix information LOG_SYS: “Sys” LOG_NET: “Net” msg:

	Message contents
Output	NA
Return	NA
Example	#include “loginfo.h” … // Set Relay state to on SendSysLog(EVT_INFO, LOG_SYS, “This is a test!”); …

Table 17: API for Log

8.9 *Alert Message Management*

Depending on platforms, SDK supports some alert API to help users send alert information while receiving specified events.

API Name	void SendAlertMsg(unsigned int msg_event, unsigned char isSysLog, MSG_SYSLOG_HANDLER *pLog)
Descriptions	The API used to send alert messages
Input	• msg_event: nessage event typedef enum { MSGALERT_COLD_START = 0, MSGALERT_AUTH_FAIL, MSGALERT_IP_CHANGE, MSGALERT_PASSWORD_CHANGE, MSGALERT_RESET_DEFAULT, MSGALERT_RESTORE_CONFIG, MSGALERT_LAN_LINK_DOWN, MSGALERT_LAN_LINK_UP, MSGALERT_DI1_CHANGE, MSGALERT_DI2_CHANGE, MSGALERT_DI1_ON, MSGALERT_DI1_OFF, MSGALERT_DI2_ON, MSGALERT_DI2_OFF, MSGALERT_OVPN_CONNECTED, MSGALERT_OVPN_DISCONNECTED, MSGALERT_PPTP_CONNECTED, MSGALERT_PPTP_DISCONNECTED, MSGALERT_UNKNOWN_COMMAND, MSGALERT_CELLULAR_LINK_DOWN, MSGALERT_CELLULAR_LINK_UP, MSGALERT_MAX MsgAlertBit_e; • isSysLog : Record the information to syslog file : No extra handle for the alert message, pMsg • pLog: pointer of MSG_SYSLOG_HANDLER typedef struct __msg_syslog_handler__ { unsigned char u8Severity; char u8PrefixMsg[16]; char u8Message[MSGALERT_MAX_LENGTH]; } MSG_SYSLOG_HANDLER;
Output	NA
Return	NA
Example	#include "alert_msg.h" ... sendAlertMsg(MSGALERT_AUTH_FAIL, 0, NULL); ...

Table 18: API for alert message management

API Name	void sendSMSMsg(unsigned int msg_event, char *pMsg)
Descriptions	This API is available only when the platform supports the cellular module and the flag of SYSFUNC_NETSVC_SMS is defined in the SDK. The API is used to send alert message through SMS of cellular module.
Input	• msg_event: nessage event typedef enum { MSGALERT_COLD_START = 0, MSGALERT_AUTH_FAIL, MSGALERT_IP_CHANGE, MSGALERT_PASSWORD_CHANGE, MSGALERT_RESET_DEFAULT, MSGALERT_RESTORE_CONFIG, MSGALERT_LAN_LINK_DOWN, MSGALERT_LAN_LINK_UP, MSGALERT_DI1_CHANGE, MSGALERT_DI2_CHANGE, MSGALERT_DI1_ON, MSGALERT_DI1_OFF, MSGALERT_DI2_ON, MSGALERT_DI2_OFF, MSGALERT_OVPN_CONNECTED, MSGALERT_OVPN_DISCONNECTED, MSGALERT_PPTP_CONNECTED, MSGALERT_PPTP_DISCONNECTED, MSGALERT_UNKNOWN_COMMAND, MSGALERT_CELLULAR_LINK_DOWN, MSGALERT_CELLULAR_LINK_UP, MSGALERT_MAX MsgAlertBit_e; • pMsg nessage contents to send out through SMS
Output	NA
Return	0: Success; Others: Failed
Example	#include “alert_msg.h” … sendSMSMsg(MSGALERT_AUTH_FAIL, “WEB authentication failed.”); …

Table 19: API for SMS message management

API Name	void sendTrapMsg(unsigned int msg_event, char *pMsg)
Descriptions	This API is available only when the flag of SYSFUNC_NETSVC_SNMP is defined in the SDK. The API is used to send alert message through SNMP trap messages.
Input	• msg_event: nessage event typedef enum { MSGALERT_COLD_START = 0, MSGALERT_WARM_START, MSGALERT_AUTH_FAIL, MSGALERT_IP_CHANGE, MSGALERT_PASSWORD_CHANGE, MSGALERT_WATCHDOG, MSGALERT_POWER_FAILURE, MSGALERT_LAN_LINK_DOWN, MSGALERT_LAN_LINK_UP, MSGALERT_RESET_DEFAULT, MSGALERT_OVPN_CONNECTED, MSGALERT_OVPN_DISCONNECTED, MSGALERT_PPTP_CONNECTED, MSGALERT_PPTP_DISCONNECTED, MSGALERT_DISTS_CHANGE, MSGALERT_NETWORK_FAILED, MSGALERT_MAX MsgAlertBit_e; • pMsg nessage contents to send out through SMS
Output	NA
Return	0: Success; Others: Failed
Example	#include “alert_msg.h” … sendTrapMsg (MSGALERT_AUTH_FAIL, “WEB authentication failed.”); …

Table 20: API for Trap message management

API Name	void sendMailMsg(unsigned int msg_event, char *pMsg)
Descriptions	This API is available only when the flag of SYSFUNC_NETSVC_MAILALERT is defined in the SDK. The API is used to send alert message through E-mail.
Input	• msg_event: nessage event typedef enum { MSGALERT_COLD_START = 0, MSGALERT_WARM_START, MSGALERT_AUTH_FAIL, MSGALERT_IP_CHANGE, MSGALERT_PASSWORD_CHANGE, MSGALERT_WATCHDOG, MSGALERT_POWER_FAILURE, MSGALERT_LAN_LINK_DOWN, MSGALERT_LAN_LINK_UP, MSGALERT_RESET_DEFAULT, MSGALERT_OVPN_CONNECTED, MSGALERT_OVPN_DISCONNECTED, MSGALERT_PPTP_CONNECTED, MSGALERT_PPTP_DISCONNECTED, MSGALERT_DISTS_CHANGE, MSGALERT_NETWORK_FAILED, MSGALERT_MAX MsgAlertBit_e; • pMsg nessage contents to send out through SMS
Output	NA
Return	0: Success; Others: Failed
Example	#include “alert_msg.h” … sendMailMsg (MSGALERT_AUTH_FAIL, “WEB authentication failed.”); …

Table 21: API for Mail message management

8.10 *Firmware Upgrade*

API Name	Int fw_upgade(char *fw_addr, int length)
Descriptions	Programming firmware to flash
Input	fw_addr: buffer address of firmware image length: length of firmware buffer
Output	NA
Return	0: Success; Others: Failed
Example	#include “sys_upgapi.h” #include “sys_reboot.h” … /* Calling firmware upgrade lib-api */ if (fw_upgrade(buff, file_size) == EXECUTE_SUCCESS) { printf("Upgrade success! (System will restart automatically after 5 secs.)\n"); sleep(5); SysRebootSystem(); } else { printf("Upgrade failed!!!!\nPlease making sure your fw image is correct and try again!\n\n"); } …

Table 22: API for firmware upgrade

API Name	Int fwupg_alloc_shmbuf(unsigned int length)
Descriptions	Allocate shared memory buffer for fw imge
Input	Buffer length(or image length) of the shared memory
Output	NA
Return	Pointer of shared memory buffer address
Example	See frmwr-upgrd.c

Table 22: API for firmware upgrade

API Name	Char *fwupg_get_shmbuf(unsigned int length)
Descriptions	Get shared memory buffer
Input	Length of firmware image

Output	NA
Return	Pointer of shared memory buffer address
Example	See <sdk>/web/cgi/firmwareUpgrade.c

Table 23: API for firmware upgrade

API Name	Char *fwupg_unlink_shmbuf()
Descriptions	Unlink shared memory buffer of firmware image
Input	NA
Output	NA
Return	NA
Example	See <sdk>/web/cgi/firmwareUpgrade.c

Table 24: API for firmware upgrade

8.11 *System Reboot*

API Name	Int SysRebootSystem(void)
Descriptions	Reboot system with the signal of “SIGTERM”
Input	NA
Output	NA
Return	NA
Example	#include “sys_reboot.h” … SysRebootSystem(); …

Table 25: API for system reboot

API Name	Int RebootSystem2(void)
Descriptions	Reboot system without the signal of “SIGTERM”
Input	NA
Output	NA
Return	NA
Example	#include “sys_reboot.h” … RebootSystem2(); …

Table 26: API for system reboot

8.12 *System Management*

API Name	Int SysBootloaderVersion(SysVersion_t *pVer) Int SysKernelVersion(SysVersion_t *pVer) Int SysAPVersion(SysVersion_t *pVer) Int SysCPLDVersion(SysVersion_t *pVer)
Descriptions	Get boot loader version Get kernel version Get AP version Get CPLD version
Input	Structure pointer of SysVersion_t
Output	Bootloader version information Kernel version information AP version information CPLD version information
Return	NA
Example	#include “ver_info.h” SysVersion_t ver; … SysBootloaderVersion(&ver); Printf(“blVer: %u.%02u”, ver.VerMajor, ver.VerMinor); SysKernelVersion(&ver); Printf(“kernelVer: %u.%02u”, ver.VerMajor, ver.VerMinor); SysAPVersion(&ver); Printf(“apVer: %u.%02u”, ver.VerMajor, ver.VerMinor); SysCPLDVersion(&ver); Printf(“cpldVer: %u.%02u”, ver.VerMajor, ver.VerMinor); …

Table 27: API for system management

API Name	Int SysStrKernelVersion(void *) Int SysStrAPVersion(void *)
Descriptions	Get kernel version Get AP version
Input	NA
Output	Kernel version information AP version information
Return	NA
Example	#include “ver_info.h” …

	printf("kernelVer: %s", SysStrKernelVersion(NULL)); printf("apVer: %s", SysStrAPVersion(NULL)); …

Table 28: API for system management

API Name	Int ExecuteSysCommand(char *cmd, int limit)
Descriptions	Execute system command (popen, pipe stream)
Input	cmd: string buffer of system command limit: limitation of reading length after command execution -1 or 0 to indicate to ignore limitation check
Output	NA
Return	0: failed; 1: success
Example	#include "sys_cmd.h" … ExecuteSysCommand("/sbin/reboot", -1); …

Table 29: API for system management

8.13 *Cellular Control (Cellular 3G/4G platform only)*

- Establishing cellular connection:

API Name	void Dial_connect(void)
Descriptions	Establish the 3G/4G connection
Input	NA
Output	NA
Return	NA
Example	#include "lib_dial.h" … Dial_connect(); …

Table 30: Estabishing cellular connection

- Terminating cellular connection:

API Name	void Dial_disconnect(void)

Descriptions	Disconnect the 3G/4G connection
Input	NA
Output	NA
Return	NA
Example	#include “lib_dial.h” … Dial_disconnect(); …

Table 31: Terminating cellular connection

- Get status information of cellular connection:

API Name	int Get_dial_info(DIAL_INFO *pInfo)
Descriptions	Get dialing status
Input	pInfo: Pointer of DIAL_INFO
Output	Dialing information
Return	Success: CMD_GET_SUCCESS Error: Others
Example	#include “lib_dial.h” DIAL_INFO dial_info; … Get_dial_info(&dial_info);

Table 32: Get status information of cellular connection

- Get GPS information (for GPS model only):

API Name	int Get_gps_info(GPS_INFO *pInfo)
Descriptions	Get GPS status
Input	pInfo: Pointer of GPS_INFO
Output	GPS information
Return	Success: CMD_GET_SUCCESS Error: Others
Example	#include “lib_dial.h” GPS_INFO gps_info; … Get_gps_info(&gps_info); …

Table 33: Get GPS information

- Check 4G support on platform:

API Name	int Sys4GSupport(void)
Descriptions	Check 4G support
Input	NA
Output	NA
Return	1: 4G function is supported on this platform 0: 4G function is not supported on this device
Example	#include “cellular_api.h” … If(Sys4GSupport()) { printf(“4G module is supported on this platform”); } …

Table 34: Get 4G support

- Check if 4G module is detected by system:

API Name	int Sys4GSupport(void)
Descriptions	Check 4G support
Input	NA
Output	NA
Return	1: 4G function is supported on this platform 0: 4G function is not supported on this device
Example	#include “cellular_api.h” … If(Sys4GSupport()) { printf(“4G module is supported on this platform”); } …

Table 35: Check 4G detection

- Get used 4G interface name:

API Name	int Sys4GInterface(char *pIf)
Descriptions	Get used 4G interface name
Input	pIf: pointer of buffer
Output	Interface name of 4G interface

Return	-1: 4G interface is not named with “eth” interface. In such case, you can read “pIf” to get 4G interface name >= 0: if 4G interface is named as “eth”, index is returned
Example	#include “cellular_api.h” Int index = -1; Char interface[16] = {0}; … If((index = Sys4GInterface(&interface)) < 0) { printf(“4G interface: %s\n”, interface); } else { printf(“4G interface: eth%d\n”, index); } …

Table 36: Get used 4G interface name

9 INI Configs Read/Write (Settings Management)

Most of the device configurations in SDK are stored in INI files. System allows some APIs to help users easily access INI files. With these APIs, users can easily access the settings by using specified feature IDs. Below are feature IDs currently supported in the SDK package:

Feature	ID
SYSCONF_FEATURE_ALL	0x00
SYSCONF_FEATURE_BOARD	0x01
SYSCONF_FEATURE_COM	0x02
SYSCONF_FEATURE_SYSTEM	0x03
SYSCONF_FEATURE_SYSLOG	0x04
SYSCONF_FEATURE_NET	0x05
SYSCONF_FEATURE_NETDNS	0x06
SYSCONF_FEATURE_PORTFORWARD	0x07
SYSCONF_FEATURE_NETWORK_3G	0x08
SYSCONF_FEATURE_NAT	0x09
SYSCONF_FEATURE_SMS	0x0A
SYSCONF_FEATURE_SNMP	0x0B
SYSCONF_FEATURE_VIP	0x0C
SYSCONF_FEATURE_OVPN	0x0D
SYSCONF_FEATURE_PPTP	0x0E
SYSCONF_FEATURE_IPSEC	0x0F
SYSCONF_FEATURE_RSTP	0x10
SYSCONF_FEATURE_URLINK	0x11
SYSCONF_FEATURE_SMTP	0x12
SYSCONF_FEATURE_OEM4	0xFA
SYSCONF_FEATURE_OEM3	0xFB
SYSCONF_FEATURE_OEM2	0xFC
SYSCONF_FEATURE_OEM1	0xFD
SYSCONF_FEATURE_OEM	0xFE

Table 37: IDs supported in SDK package

Note: Feature settings are available only when the specified functions are available in the SDK support list.

9.1 *Read configurations from shared memory*

API Name	Int SysConf_Get_Shmcfg(unsigned char u8Id, void *pConf)
Descriptions	Based on feature ID to read configurations from shared memory to pConf
Input	u8Id: Feature ID
Output	pConf: pointer of buffer
Return	0: Success; -1: Failed
Example	#include “shmapi.h” #include “net_conf.h” … NET_CONFIG conf[MAX_NIC_UMBER]; // Read NET configuration from shared memory SysConf_Get_Shmcfg(SYSCONF_FEATURE_NET, &conf[0]); …

Table 38: Read config from shared memory

API Name	Int SysConf_Shm_GetKey(unsigned char u8Id, void *pConf, char *key, char *val)
Descriptions	Based on feature ID and configuration pointer (pConf) to get value of specified key
Input	u8Id: Feature ID pConf: pointer of feature configurations key: Key string in INI file
Output	val: key value
Return	0: Success; -1: Failed
Example	#include “shmapi.h” #include “net_conf.h” NET_CONFIG conf[MAX_NIC_NUMBER]; char ip[16] = {0}; // Read NET configuration from shared memory ***SysConf_Get_Shmcfg(SYSCONF_FEATURE_NET, &conf[0]);*** … // Read IPv4 Address ***SysConf_Shm_GetKey(SYSCONF_FEATURE_NET, &conf[0], NET_KEY_IP4_ADDR, ip);***

Table 39: Read config from shared memory

API Name	Int SysConf_Get_ShmKey(unsigned char u8Id, unsigned char section, char *key, char *val)
Descriptions	Based on feature ID and section index to read value of specified key from shared memory
Input	u8Id: Feature ID section: Section index in INI file key: Key string in INI file
Output	val: key value
Return	0: Success; -1: Failed
Example	#include “shmapi.h” #include “system_conf.h” … char user[32] = {0}; char pass[32] = {0}; … // Read user name and password ***SysConf_Get_ShmKey(SYSCONF_FEATURE_SYSTEM, 0, SYSTEM_KEY_USERNAME, user);*** ***SysConf_Get_ShmKey(SYSCONF_FEATURE_SYSTEM, 0, SYSTEM_KEY_PASSWORD, pass);*** …

Table 40: Read config from shared memory

9.2 *Set configuration to shared memory*

API Name	Int SysConf_Shm_SetKey(unsigned char u8Id, void *pConf, char *key, char *val)
Descriptions	Based on feature ID to set value of specified key to pConf
Input	u8Id: Feature ID pConf: pointer of feature configurations key: Key string in INI file val: key value
Output	NA
Return	0: Success; -1: Failed

Example	#include “shmapi.h” #include “net_conf.h” … NET_CONFIG conf[MAX_NIC_ NUMBER]; char ip[16] = “192.168.5.123”; // Read original NET configuration from shared memory SysConf_Get_Shmcfg(SYSCONF_FEATURE_NET, &conf[0]); … // Update IPv4 Address ***SysConf_Shm_SetKey(SYSCONF_FEATURE_NET, &conf[0], NET_KEY_IP4_ADDR, ip);*** …

Table 41: Set config to shared memory

API Name	Int SysConf_Set_Shmcfg(unsigned char u8Id, void *pConf)
Descriptions	Based on feature ID to write configurations to shared memory
Input	u8Id: Feature ID pConf: pointer of buffer
Output	NA
Return	0: Success; -1: Failed
Example	#include “shmapi.h” #include “system_conf.h” … NET_CONFIG conf[MAX_NIC_ NUMBER]; char ip[16] = “192.168.5.123”; // Read original NET configuration from shared memory SysConf_Get_Shmcfg(SYSCONF_FEATURE_NET, &conf[0]); … // Update IPv4 Address ***SysConf_Shm_SetKey(SYSCONF_FEATURE_NET, &conf[0], NET_KEY_IP4_ADDR, ip);*** … ***// Update Configurations to shared memory*** ***SysConf_Set_Shmcfg(SYSCONF_FEATURE_NET, &conf[0]);***

Table 42: Set config to shared memory

9.3 *Update Configurations to INI files*

API Name	Int SysConf_Update_Shmcfg(unsigned char u8Id, void *pConf)
Descriptions	Based on feature ID to update feature configurations to shared memory and INI file
Input	u8Id: Feature ID pConf: pointer of buffer
Output	NA
Return	0: Success; -1: Failed
Example	#include “shmapi.h” #include “com_conf.h” … // Change COM port mode to RS-232 SysConf_Shm_SetKey(SYSCONF_FEATURE_COM, &conf[0], COM_KEY_MODE, “0”); … // Update IPv4 Address ***SysConf_Shm_SetKey(SYSCONF_FEATURE_NET, &conf[0], NET_KEY_IP4_ADDR, ip);*** … ***// Update Configurations to shared memory and INI file simutaneously*** ***SysConf_Update_Shmcfg(SYSCONF_FEATURE_NET, &conf[0]);***

Table 43: Update config to INI files

API Name	Int SysConf_Update_ShmKey(unsigned char u8Id, unsigned char section, char *key, char *value)
Descriptions	Based on feature ID to update key value to shared memory and INI file
Input	u8Id: Feature ID pConf: pointer of buffer
Output	NA
Return	0: Success; -1: Failed
Example	#include “shmapi.h” #include “com_conf.h” ***// Update Password:”12345678” to shared memory and INI file*** ***SysConf_Update_ShmKey(SYSCONF_FEATURE_SYSTEM, 0, SYSTEM_KEY_PASSWORD, “12345678”);***

Table 44: Update config to INI files

9.4 *Add new configurations*

The SDK package already provides an example for users to easily implement the INI feature settings. Here are the following steps which need to be undertaken:

1. Example of feature configurations:

   <sdk>/software/include/sysconf.h
   <sdk>/software/library/conf/oem_conf.h
   <sdk>/software/library/conf/conf_handler.c (required while adding/modifying the feature name)

2. Define the feature ID in "<sdk>/software/include/sysconf.h"

   # vi <sdk>/software/include/sysconf.h

```
typedef enum {
    SYSCONF_FEATURE_ALL          = 0x00,
    SYSCONF_FEATURE_BOARD        = 0x01,
    SYSCONF_FEATURE_COM          = 0x02,
    SYSCONF_FEATURE_SYSTEM       = 0x03,
    SYSCONF_FEATURE_SYSLOG       = 0x04,
    SYSCONF_FEATURE_NET          = 0x05,
    SYSCONF_FEATURE_NETDNS       = 0x06,
    SYSCONF_FEATURE_PORTFORWARD  = 0x07,
    SYSCONF_FEATURE_NETWORK_3G   = 0x08,
    SYSCONF_FEATURE_NAT          = 0x09,
    SYSCONF_FEATURE_SMS          = 0x0A,
    SYSCONF_FEATURE_SNMP         = 0x0B,
    SYSCONF_FEATURE_VIP          = 0x0C,
    SYSCONF_FEATURE_OVPN         = 0x0D,
    SYSCONF_FEATURE_PPTP         = 0x0E,
    SYSCONF_FEATURE_IPSEC        = 0x0F,
    SYSCONF_FEATURE_RSTP         = 0x10,
    SYSCONF_FEATURE_URLINK       = 0x11,
    SYSCONF_FEATURE_SMTP         = 0x12,
    /* add your own feature type before "OEM" */
    SYSCONF_FEATURE_OEM4         = 0xFA,
    SYSCONF_FEATURE_OEM3         = 0xFB,
    SYSCONF_FEATURE_OEM2         = 0xFC,
    SYSCONF_FEATURE_OEM1         = 0xFD
    SYSCONF_FEATURE_OEM          = 0xFE,
    SYSCONF_FEATURE_UNKNOWN
} SYSCONF_FEATURE;
```

Figure 20: Defining feature ID

3. Define the feature section name and supported keys in "<sdk>/software/include/oem_conf.h"

   # vi <sdk>/software/include/oem_conf.h

```
#ifndef _OEM_CONFIG_H_
#define _OEM_CONFIG_H_
                                INI file name
#define OEM_CFG_FILE            "/jffs2/conf/oemcfg.ini"

#define OEM_SECT_NAME           "oem"
#define OEM_KEY_RSV1            "oem_rsv_1"
#define OEM_KEY_RSV2            "oem_rsv_2"
#define OEM_KEY_RSV3            "oem_rsv_3"
#define OEM_KEY_RSV4            "oem_rsv_4"
                                section name and supported key strings in INI file
#define MAX_OEMCFG_KEY          4
                                Max. keys
extern SYSCONF_KEY g_OEMCfgKey[];
```

Figure 21: Defining feature section name

4. Define a structure to handle settings in "<sdk>/software/include/oem_conf.h"

vi <sdk>/software/include/oem_conf.h

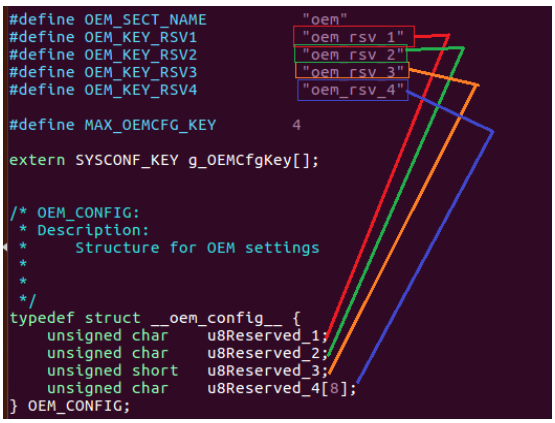


Figure 22: Defining structure to handle SDK settings

5. Define function names that are used to init/read/write feature settings

   # vi <sdk>/software/include/oem_conf.h

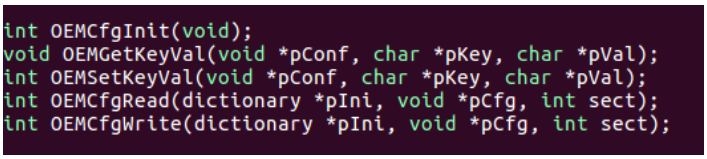


Figure 23: Defining function names for feature settings

6. Add the ID of "SYSCONF_FEATURE_OEM" in gSYSConfHadnler[] in

   "<sdk>/software/library/conf/conf_handler.c"

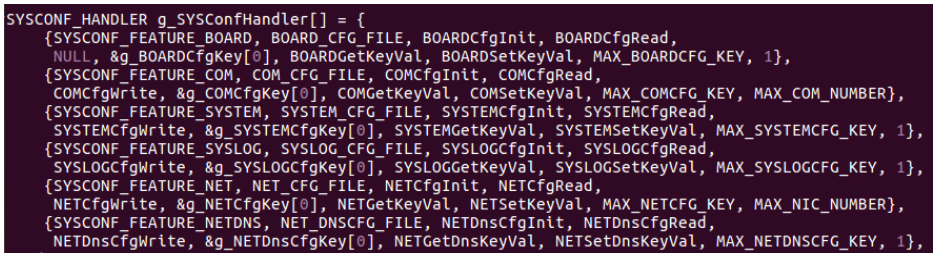


Figure 24: Add sysconfig ID

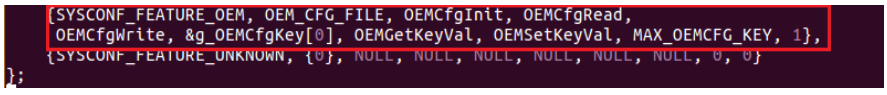


Figure 25: Add sysconfig ID

7. Define the key mapping table in "<sdk>/software/library/conf/oemconf.c"

vi <sdk>/software/library/conf/oemconf.c

```
SYSCONF_KEY g_OEMCfgKey[] =
{
    {SYSCONF_KEYTYPE_INT, 0, OEM_SECT_NAME, OEM_KEY_RSV1},
    {SYSCONF_KEYTYPE_INT, 0, OEM_SECT_NAME, OEM_KEY_RSV2},
    {SYSCONF_KEYTYPE_INT, 0, OEM_SECT_NAME, OEM_KEY_RSV3},
    {SYSCONF_KEYTYPE_STR, 0, OEM_SECT_NAME, OEM_KEY_RSV4},
    {SYSCONF_KEYTYPE_UNKNOWN, 0, {0}, {0}}
};
```

Figure 26: Defining key mapping table

8. Implement init function in“<sdk>/software/library/conf/oemconf.c”

vi <sdk>/software/library/conf/oemconf.c

```
int OEMCfgInit(void)
{
    int ret = -1;
    FILE *pf = NULL;

    DBGPRINT("%s, Initialize configurations to %s\n", __func__, OEM_CFG_FILE);
    pf = fopen(OEM_CFG_FILE, "w");
    if (pf == NULL) {
        DBGPRINT("Unable to open file: %s\n", OEM_CFG_FILE);
        return ret;
    }
    fprintf(pf,
            "\n[%s] \n"
            "%s    = %s\n"
            "%s    = %s\n"
            "%s    = %s\n"
            "%s    = %s\n"
            "\n", OEM_SECT_NAME, OEM_KEY_RSV1, DEFCONF_OEM_RSV1,
                    OEM_KEY_RSV2, DEFCONF_OEM_RSV2,
                    OEM_KEY_RSV3, DEFCONF_OEM_RSV3,
                    OEM_KEY_RSV4, DEFCONF_OEM_RSV4);

    fclose(pf);
    ret = 0;

    return ret;
}
```

Figure 27: Implementing init function

```
int OEMCfgInit(void)
{
    int ret = -1;
    FILE *pf = NULL;

    DBGPRINT("%s, Initialize configurations to %s\n", __func__, OEM_CFG_FILE);
    pf = fopen(OEM_CFG_FILE, "w");
    if (pf == NULL) {
        DBGPRINT("Unable to open file: %s\n", OEM_CFG_FILE);
        return ret;
    }
    fprintf(pf,
            "\n[%s] \n"
            "%s    = %s\n"
            "%s    = %s\n"
            "%s    = %s\n"
            "%s    = %s\n"
            "\n", OEM_SECT_NAME, OEM_KEY_RSV1, DEFCONF_OEM_RSV1,
                    OEM_KEY_RSV2, DEFCONF_OEM_RSV2,
                    OEM_KEY_RSV3, DEFCONF_OEM_RSV3,
                    OEM_KEY_RSV4, DEFCONF_OEM_RSV4);

    fclose(pf);
    ret = 0;

    return ret;
}
```

Figure 28: Implementing init function

9. Implement read function in“<sdk>/software/library/conf/oemconf.c”

vi <sdk>/software/library/conf/oemconf.c

```c
int OEMCfgRead(dictionary *pIni, void *pCfg, int sect)
{
    int ret = -1;
    char *pStrVal = NULL;
    OEM_CONFIG *pConf = (OEM_CONFIG *) pCfg;
    int  i = 0;

    // make sure ther are keys for the section
    if ( 0 < iniparser_getsecnkeys(pIni, OEM_SECT_NAME)) {
        for (i = 0; i < MAX_OEMCFG_KEY; i++) {
            pStrVal = SYSGetINIStrValue(pIni, g_OEMCfgKey[i].section, g_OEMCfgKey[i].key);
            if (pStrVal == NULL || OEMSetKeyVal(pConf, g_OEMCfgKey[i].key, pStrVal) < 0) {
                break;
            } else {
                DBGPRINT("%s: [%s]\n", g_OEMCfgKey[i].key, pStrVal);
                ret = 0;
            }
        }
    } else {
        fprintf(stderr, "Unable to find section [%s]\n", OEM_SECT_NAME);
    }


    return ret;
}
```

Figure 29: Implementing read function

10. Implement write function in“<sdk>/software/library/conf/oemconf.c”

vi <sdk>/software/library/conf/oemconf.c

```c
int OEMCfgWrite(dictionary *pIni, void *pCfg, int sect)
{
    int ret = -1;
    char a_KeyVal[32] = {0};
    OEM_CONFIG *pOEMConf = (OEM_CONFIG *) pCfg;
    int i = 0;


    // make sure ther are keys for the section
    if ( 0 < iniparser_getsecnkeys(pIni, OEM_SECT_NAME)) {
        for (i = 0; i < MAX_OEMCFG_KEY; i++) {
            memset(a_KeyVal, 0, sizeof(a_KeyVal));
            OEMGetKeyVal(pOEMConf, g_OEMCfgKey[i].key, a_KeyVal);
            if ((ret = SYSSetKeyValue(pIni, g_OEMCfgKey[i].section, g_OEMCfgKey[i].key, a_KeyVal)) < 0) {
                break;
            } else {
                ret = 0;
            }
        }
    } else {
        fprintf(stderr, "Unable to find section [%s]\n", OEM_SECT_NAME);
    }

    return ret;
}
```

Figure 30: Implementing write function

11. Implement key get function in“<sdk>/software/library/conf/oemconf.c”

vi <sdk>/software/library/conf/oemconf.c

```
int OEMSetKeyVal(void *pConf, char *pKey, char *pVal)
{
    int ret = 0;
    OEM_CONFIG *pConfig = (OEM_CONFIG *) pConf;

    if (strncmp(pKey, OEM_KEY_RSV1, strlen(OEM_KEY_RSV1)) == 0) {
        pConfig->u8Reserved_1 = (atoi(pVal))? 1 : 0;
    } else if (strncmp(pKey, OEM_KEY_RSV2, strlen(OEM_KEY_RSV2)) == 0) {
        pConfig->u8Reserved_2 = (atoi(pVal))? 1 : 0;
    } else if (strncmp(pKey, OEM_KEY_RSV3, strlen(OEM_KEY_RSV3)) == 0) {
        pConfig->u8Reserved_3 = (unsigned short)(atoi(pVal));
    } else if (strncmp(pKey, OEM_KEY_RSV4, strlen(OEM_KEY_RSV4)) == 0) {
        strncpy((char *)pConfig->u8Reserved_4, pVal, 8);
    } else {
        strcpy(pVal, "Unknown");
        ret = -1;
    }

    return ret;
}
```

Figure 31: Implementing key get function

12. Implement key set function in“<sdk>/software/library/conf/oemconf.c”

    # vi <sdk>/software/library/conf/oemconf.c

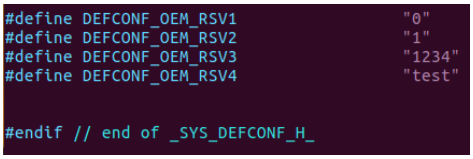
```
int OEMSetKeyVal(void *pConf, char *pKey, char *pVal)
{
    int ret = 0;
    OEM_CONFIG *pConfig = (OEM_CONFIG *) pConf;

    if (strncmp(pKey, OEM_KEY_RSV1, strlen(OEM_KEY_RSV1)) == 0) {
        pConfig->u8Reserved_1 = (atoi(pVal))? 1 : 0;
    } else if (strncmp(pKey, OEM_KEY_RSV2, strlen(OEM_KEY_RSV2)) == 0) {
        pConfig->u8Reserved_2 = (atoi(pVal))? 1 : 0;
    } else if (strncmp(pKey, OEM_KEY_RSV3, strlen(OEM_KEY_RSV3)) == 0) {
        pConfig->u8Reserved_3 = (unsigned short)(atoi(pVal));
    } else if (strncmp(pKey, OEM_KEY_RSV4, strlen(OEM_KEY_RSV4)) == 0) {
        strncpy((char *)pConfig->u8Reserved_4, pVal, 8);
    } else {
        strcpy(pVal, "Unknown");
        ret = -1;
    }

    return ret;
}
```

Figure 32: Implementing key set function

13. Edit default configurations in <sdk>/config/<targte>/defconf.h



```
#define DEFCONF_OEM_RSV1                "0"
#define DEFCONF_OEM_RSV2                "1"
#define DEFCONF_OEM_RSV3                "1234"
#define DEFCONF_OEM_RSV4                "test"


#endif // end of _SYS_DEFCONF_H_
```

Figure 33: Edit default configurations

14. Compile the software to make sure no error happened

    # make swbuild

15. Build the system and burn to target device

16. Open debug console, and run this command to check if feature settings are working

    # confutil -c 254 -r 6

```
# confutil -c 254 -r 6

[0xfe, Sec. #: 1](oemcfg.ini): OEM Configurations
    - oem_rsv_1
    - oem_rsv_2
    - oem_rsv_3
    - oem_rsv_4
```

Figure 34: Running commands in open debug console

17. Run these commands to check each key values from debug console:

```
# confutil -c 254 -r 3 -k oem_rsv_1
0
# confutil -c 254 -r 3 -k oem_rsv_2
1
# confutil -c 254 -r 3 -k oem_rsv_3
1234
# confutil -c 254 -r 3 -k oem_rsv_4
test
```

Figure 35: Running commands in open debug console

18. Running these commands to change key values and check if the function works:

```
# confutil -c 254 -r 4 -k oem_rsv_1 -v 1
# confutil -c 254 -r 4 -k oem_rsv_2 -v 2
# confutil -c 254 -r 4 -k oem_rsv_3 -v 5678
# confutil -c 254 -r 4 -k oem_rsv_4 -v test1234
# confutil -c 254 -r 3 -k oem_rsv_1
1
# confutil -c 254 -r 3 -k oem_rsv_2
2
# confutil -c 254 -r 3 -k oem_rsv_3
5678
# confutil -c 254 -r 3 -k oem_rsv_4
test1234
#
```

Figure 36: Running commands in open debug console

10 Software

The software folder in SDK collects common libraries and applications.

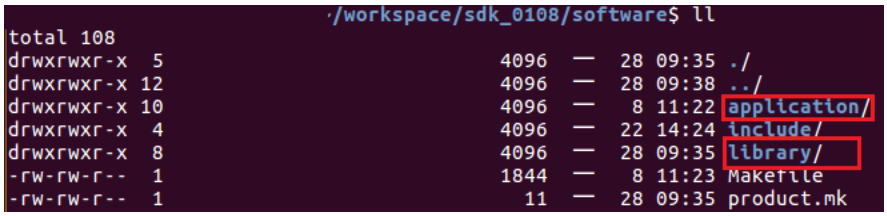


Figure 37: Software folder in SDK

10.1 *Application*

Folder	Descriptions
system	This folder collects common applications and scripts
utils	This folder collects diagnostic tools

Table 45: Software application folder

10.2 *Library*

Folder	Descriptions
common	This folder collects common libraries, such as platform IO access
conf	This folder collects the libraries related to the INI files access
eeprom	This folder collects the libraries related to the EEPROM access
firewall	This folder collects the libraries related to the Firewall operations
mobile	This folder collects the libraries related to the 3G/4G module control

Table 46: Software library folder

11 Web

SDK package supports the simple WEB server with “lighttpd”.(Defaul Address: http://10.0.50.100 or https://192.168.1.100) The CGI files and WEB pages are placed in these directories:

- CGI Files: <SDK>/webs/lighttpd/cgi/
- WEB Pages: <SDK>/webs/lighttpd/web_pages/

11.1 *Web Account/Password*

Default WEB account and password:

- User Name: admin
- Password: default

11.2 *Change Web Logo*

Please replacing the default image file with your own logo:
<sdk>/webs/lighttpd/web_pages/images/logo.gif

- Width: 200px
- Height: 48px

11.3 *Add a new page in selection menu*

Ref File: <sd>/webs/lighttpd/web_pages/javascript/quickmenu.js

```
...
var menuItem = [
   {parent: '', name: 'System Status', web: ''},
   {parent: 'System Status', name: 'Overview', web: 'Overview.html'},
   {parent: '', name: 'Log Settings', web: ''},
   {parent: 'Log Settings', name: 'System Log Settings', web: 'sysLogSettings.html'},
   {parent: 'Log Settings', name: 'System Log', web: 'sysLog.html'},
   {parent: '', name: 'System Setup', web: ''},
   {parent: 'System Setup', name: 'Admin Settings', web: 'Security.html'},
   {parent: 'System Setup', name: 'Firmware Upgrade', web: 'firmwareUpgrade.html'},
   {parent: 'System Setup', name: 'Restore Configuration', web: 'importExport.html'},
   {parent: '', name: 'Reboot', web: 'Reboot.html'}
];
...
```

Figure 38: Add new page in selection menu

12 System

In SDK repository, most configurations are placed under "***<SDK>/config/<Target>/***" folder. The figure below illustrates contents of target configurations:

```
drwxr-xr-x 2 benv benv  4096  九   3 15:29 ./
drwxr-xr-x 3 benv benv  4096  九   3 15:29 ../
-rw-r--r-- 1 benv benv    29  九   3 08:25 ATSDKCNR_A2201.h
-rw-r--r-- 1 benv benv 26887  九   2 10:17 default.dat
-rw-r--r-- 1 benv benv 12751  九   2 08:29 defconf.h
-rw-r--r-- 1 benv benv  1747  九   2 08:29 function.conf
-rw-r--r-- 1 benv benv   330  九   3 15:26 model_dep.h
-rw-r--r-- 1 benv benv 69469  九   2 14:34 plat_defconfig
-rw-r--r-- 1 benv benv   676  九   3 15:26 platform.conf
-rw-r--r-- 1 benv benv   262  九   3 15:29 sys_ver.h
```

Figure 39: System target configurations

12.1 *System start script files*

- In user space, system start-up scripts are put under "<sdk>/filesystem/etc/init.d/"
- System initializes all features' settings in ***S01logging***

```
#!/bin/sh

...
/usr/bin/confutil -c 0 -r 1
...
```

Figure 40: System start script files

- ATOP's main initial flow is implemented in ***S21SysInit***

12.2 *Account and password of Debug Console*

- User Name: root
- Password: NULL

12.3 *Change System Version Information*

Ref: <SDK>/config/<target>/platform.conf

```
# Boot Loader Version
export BLVer=01.20
# Signature
export signature=
# Software App Version
export APVer=01.01
# Kernel Version
export KERVer=03.10
```

Figure 41: Changing system version information

Run this command to rebuild the library, and update version information:

make swbuild; make image;
make swbuild; make fwimg;

12.4 *Platform Default Configurations*

The initial system settings of the project are configured in "<SDK>/config/<Target>/default.dat". Users can easily change each project's default settings in this file.

```
[system]
username    = admin
password    = default
hostname    = hostname
ntp_enable    = Disable
ntp_status    = Disable
ntp_timezone    = 0
ntp_server    = 0.0.0.0
ntp_dls_enable    = Disable
ntp_dls_month_b    = 3
ntp_dls_date_b    = 0
ntp_dls_week_b    = 2
ntp_dls_hour_b    = 12
ntp_dls_month_e    = 10
ntp_dls_date_e    = 3
ntp_dls_week_e    = 3
ntp_dls_hour_e    = 12
ntp_dls_hr_off    = 0
web_mode    = 1
telnet_en    = 1
ssh_en    = 1
modbus_slave_id    = 255
modbus_port    = 65535
relay_bmap    = 0
relay_outtime    = 0

[net_00]
ip4_mode    = Static
ip6_mode    = 1
ip6_prefix    = 64
lan_speed    = 100
mac    = 00:60:e9:22:d6:73
ip4_addr    = 192.168.1.100
```

Figure 42: Platform default configurations

12.5 *Kernel Configurations*

The project's kernel configuration file is "***<SDK>/config/<TARGET>/plat_defconfig***".

To change it, you may execute below commands to enable/disable configurations:

```
// Switch to kernel folder
# cd <SDK>/kernel/linux

// Running menuconfig command
Make arch=ARM
CROSS_COMPILE=/opt/ti-am335x-linux-devkit-08.00.00.00/bin/arm-linux-gnueabihf-
menuconfig

// Edit kernel support and save configurations
// Copy the new configurations to the target folder
# cp .config <SDK>/config/<Target>/plat_defconfig
```

Figure 43: Kernel Configurations

12.6 *Flash Layout*

ATOP SDK limits the modification of flash partition. We do not recommend that users update the flash layout, as the flash partitions are pre-defined in HW configurations. ATOP SDK provides the HW configurations in binary format. If users indeed needed to modify the flash layout, customers can request a layout update before product shipment.

12.7 *Change COM Number*

The physical COM port support varies with platforms. If the physical COM number is not matched with your platform, you can modify it using the below file:

<sdk>/software/include/sys_uart.h

```
#ifndef _SYS_UART_H
#define _SYS_UART_H

#define COM_PORT_NUM    16

/* Define serial module */
#define NO_MODULE                       7
#define RS232_MODULE                    6
#define RS485_MODULE                    5
#define RS485_ISO_8PORT_MODULE          5
#define RS232_RS422_RS485_MODULE        4
#define RS422_RS485_ISO_8PORT_MODULE    1
#define RS232_ISO_8PORT_MODULE          0

int SysUARTNumber(void);
int uart_init_set(int);
#endif
```

Figure 44: Change COM number

13 SMS Managemet (3G/4G Cellular Only)

ATOP SDK provides a simple mechanism for users to easily manage SMS with sms tools.

Note: Before using it, please make sure the SIM is ready on your device.

13.1 *SMS Settings*

In SDK SMS settings are managed in this structured container:

```
/* SMS_CONFIG:
 * Description:
 *     Structure for SMS settings
 *
 *
 */
typedef struct __sms_config__ {
    unsigned char    u8Mode;                                    /*<-- 0: disabled; 1: free; 2: restricted                    */
    unsigned char    u8Reply;                                   /*<-- Enable/disable SMS reply                               */
    unsigned char    u8Reserved[2];                             /*<-- Reserved                                               */
    char             a_u8Password[SMS_BUFFER_LEN];              /*<-- Passowrd for the remote control                        */
    char             a_u8Message[SMS_MESSAGE_LEN];              /*<-- Unknown message                                        */
    char             a_u8Alias[MAX_SMS_PHONE_NUM][SMS_BUFFER_LEN];      /*<-- Alias of the Phone                             */
    char             a_u8PhoneNum[MAX_SMS_PHONE_NUM][SMS_BUFFER_LEN];   /*<-- Phone number                                   */
    unsigned int     u32RemotAccess[MAX_SMS_PHONE_NUM];         /*<-- Remote Control Capability of the Phone                 */
    unsigned int     u32AlertBitMap[MAX_SMS_PHONE_NUM];         /*<-- Alert Control Bit of the Phone                         */
    unsigned char    u8AltMsgDelay[MAX_SMS_ALERT_NUM];          /*<-- SMS dealy interval 0 - 255                             */
} SMS_CONFIG;
```

Figure 45: SMS Settings

Field	Description
u8Mode	SMS management mode • 0 : Disable • 1: Free, no limitation • 2: Restricted, only configured phone number is available
u8Reply	Enable/Disable SMS reply when receiving SMS remote control command
a_u8Password	Password of SMS remote control (max. 16 characters)
a_u8Message	Messages to reply when receiving a unknown remote control command (max 64 characters)
a_u8Alias	Alias of phone number (max. 5 phone numbers,)
a_u8PhoneNum	Phone number Default MAX_SMS_PHONE_NUM is 5
a_u8RemoteAccess	Enable/Disable remote control of each phone number
a_u8AlertBitMap	Bit map of alert event for each phone number
a_u8AltMsgDelay	Alert messages delay interval of each alert event.

Table 47: SMS Settings

To access the SMS settings, please refer to the “Ch8. INI Configurations Read/Write (Settings Management)”.

13.2 *SMS Remote Control*

- Control Message Format

#<Password of SMS control>#<SMS control messages>

Example:

- Password of SMS control: “12345678”
- SMS control message: “echo_test”
- Users send remote control message:
  #12345678#echo_test

- SMS Event Handler
  The script file used to handle the SMS event is

  <sdk>/3rdparty/patch/smstools3-3.1.21/scripts/smsevent

- SMS Remote Control Command List:
  The file used to define supported remote SMS control message are stored at below file

  <sdk>/3rdparty/patch/smstools3-3.1.21/smscmd.lst

13.3 *SMS Alert Messages*

See ***7-9. Alert Message Control*** to get idea how to access SMS settings through APIs.

Here are the steps to enable alert messages:

1. Set SMS management mode to “free”

```
# confutil -c 10 -r 4 -k mode -v free
```

2. Set the alias for the phone 1 as “phone_1”

```
# confutil -c 10 -r 4 -k alias00 -v phone_1
```

3. Set the phone number for phone 1

4. Set the Alert control to 63 (Bit 0 - 5)

```
# confutil -c 10 -r 4 -k devAlert00 -v 63
```

5. Check the configurations:

```
# confutil -d -f /jffs2/conf/smsconf.ini
Initialize cfg to file: /jffs2/conf/smsconf.ini
[sms]=UNDEF
[sms:mode]=[disabled]
[sms:password]=[]
[sms:reply]=[0]
[sms:message]=[Unknown Msg.]
[sms:alias00]=[phone_1]
[sms:number00]=[0900123456]
[sms:rmtaccess00]=[0]
[sms:devalert00]=[63]
```

Figure 46: SMS Configuration

6. Change IP address from your WEB and check if you can receive the alert message:

Figure 47: SMS Alert message

13.4 *SMS Remote Control*

Please follow the following steps:

1. Set SMS management mode to “free”

```
# confutil -c 10 -r 4 -k mode -v free
```

2. Enable SMS reply

```
# confutil -c 10 -r 4 -k reply -v 1
```

3. Set the remote control password

```
# confutil -c 10 -r 4 -k password -v "12345678"
```

4. Check the configurations:

```
# confutil -d -f /jffs2/conf/smsconf.ini
Initialize cfg to file: /jffs2/conf/smsconf.ini
[sms]=UNDEF
[sms:mode]=[free]
[sms:password]=[12345678]
[sms:reply]=[1]
[sms:message]=[Unknown Msg.]
[sms:alias00]=[]
[sms:number00]=[]
[sms:rmtaccess00]=[0]
```

Figure 48: SMS remote control configuration

5. Send a message to the device (Suppose the phone number is “0901123456”)

   *Note: SMS remote control message format is: **“#<password>#<command>”***
   # sendsms 0901123456 “#12345678#echo_test”

6. Check remote control response.
   The number will receive a SMS messages: “SMS self test!”

Figure 49: SMS Self Test

14 Firewall Support (Gateway Platform Only)

For ATOP's gateway platform, SDK provides the basic firewall rules with "iptables". In SDK, the firewall is activated when the NAT function is enabled. Users can reference the start-up script file to implement proprietary firewall mechanism.

- Script file to set the firewall

  <sdk>/software/application/system/firewall.sh

- Firewall script activation
  When the WAN interface is up, system will activate the firewall script file

  <sdk>/application/system/if-up.sh

14.1 *NAT*

The NAT settings are managed in below container:

```
/* NAT_CONFIG:
 * Description:
 *     Structure for NAT settings
 *
 *
 */
typedef struct __nat_config__ {
    unsigned char    u8NATEnable;                /*<-- NAT enable/disable
    unsigned char    u8DHCPSvrEnable;            /*<-- DHCP Server enable/disable
    unsigned char    u8WanIf;                    /*<-- WAN interface
    unsigned char    u8Reserved;                 /*<-- Reserved
    unsigned char    a_u8IPStart[4];             /*<-- DHCP server: start address of IP pool
    unsigned char    a_u8IPEnd[4];               /*<-- DHCP server: end address of IP pool
} NAT_CONFIG;
```

Figure 50: Firewall NAT

Field	Description
u8NATEnable	NAT enable/disable • 0 : Disable • 1: Enable
u8DHCPSvrEnable	When NAT is enabled, users can determine to enable/disable DHCP server function on local LAN DHCP server enable/disable • 0 : Disable • 1: Enable
a_u8WanIF	Index of WAN interface. The filed would be useful only when there are two LAN interfaces supported on the platform
a_u8IPStart	Start IP addresses that DHCP server to assign
a_u8IPEnd	End IP addresses that DHCP server to assign

Table 48: NAT Settings

14.2 *Firewall Scripts: Deny/Allow/Forward*

SDK provide the simple mechanism to allow users to activate firewall on device. Users can easily establish their own firewall on their gateway device by adding/creating their rules in these shell script files.

- /etc/iptables/iptables.deny
- /etc/iptables/iptables.allow
- /etc/iptables/port_forward

When firewall.sh runs and upper script files exist, the related script would be activated.

15 Examples

Add a new daemon in SDK:

SDK provides the example code of com_tcp_server in software folder.
The com_tcp_server (“<SDK>/software/application/utils/com_tcp_server”) is an example used to exchange data between COM port and network. Users can reference the example code (tcp_server.c and Makefile) to get an idea how to create a daemon in the system.

16 Warranty

Limited Warranty Conditions

Products supplied by Atop Technologies Inc. are covered in this warranty for undesired performance or defects resulting from shipping, or any other event deemed to be the result of Atop Technologies Inc. mishandling. The warranty doesnot cover; however, equipment which has been damaged due to accident, misuse, abuse, such as:

- Use of incorrect power supply, connectors, or maintenance procedures
- Use of accessories not sanctioned by us
- Improper or insufficient ventilation
- Improper or unauthorized repair
- Replacement with unauthorized parts
- Failure to follow our operating Instructions
- Fire, flood, "Act of God", or any other contingencies beyond our control.

RMA and Shipping Reimbursement

- Customers must always obtain an authorized **"RMA" number** from us before shipping the goods to be repaired.
- When in normal use, a sold product shall be replaced with a new one within 3 months upon purchase. The shipping cost from the customer to us will be reimbursed.
- After 3 months and still within the warranty period, it is up to us whether to replace the unit with a new one; normally, as long as a product is under warranty, all parts and labour are free-of-charge to the customers.
- After the warranty period, the customer shall cover the cost for parts and labour.
- Three months after purchase, the shipping cost from the customer to us will not be reimbursed, but the shipping costs from us to the customer will be paid by us.

Limited Liability

Atop Technologies Inc. shall not be held responsible for any consequential losses from using our products.

Warranty

Atop Technologies Inc. provides a 5-year maximum warranty for Industrial Serial Device Server products.

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